

Human Allied Artificial Intelligence

Harsha Kokel, Sriraam Natarajan



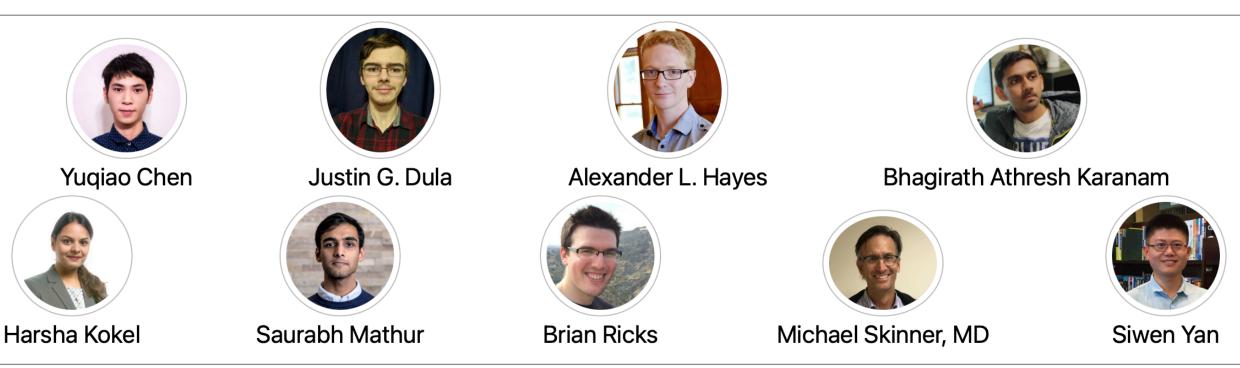
St RLingLAB L

Lab Members

Who we are!



Sriraam Natarajan



Who we are!

Alumni (PhD)

Nandini Ramanan, Navdeep Kaur, Srijita Das, Devendra Singh Dhami, Mayukh Das, Phillip Odom, Shuo Yang, Tushar Khot

Key Collaborators

Kristian Kersting, Jude Shavlik, Gautam Kunapuli, Prasad Tadepalli, David Page, Dan Roth, Jana Doppa, Ron Parr, Predrag Radivojac, William Cohen, David Poole, Kay Connelly, Balaraman Ravindran, Clinical collaborators

Funding agencies

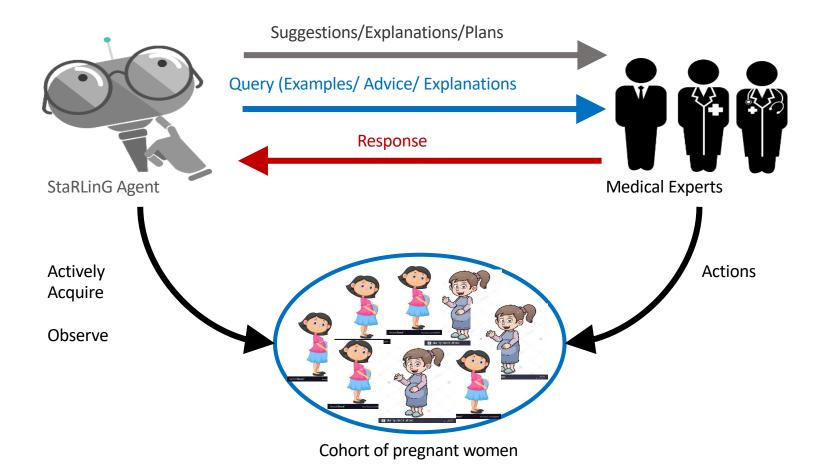
DARPA (Minerva, CwC, DEFT & Machine Reading), NSF (EAGER & SCH), AFRL, ARO (YIP, STIR), AFOSR (SBIR), NIH (R01), Indiana (Precision Medicine), XEROX PARC, Amazon, Intel, TURVO and Verisk Inc.

What is Human Allied AI?



Can we build systems that can seamlessly interact with, learn from, collaborate with and potentially teach the human expert?

What is Human Allied AI?



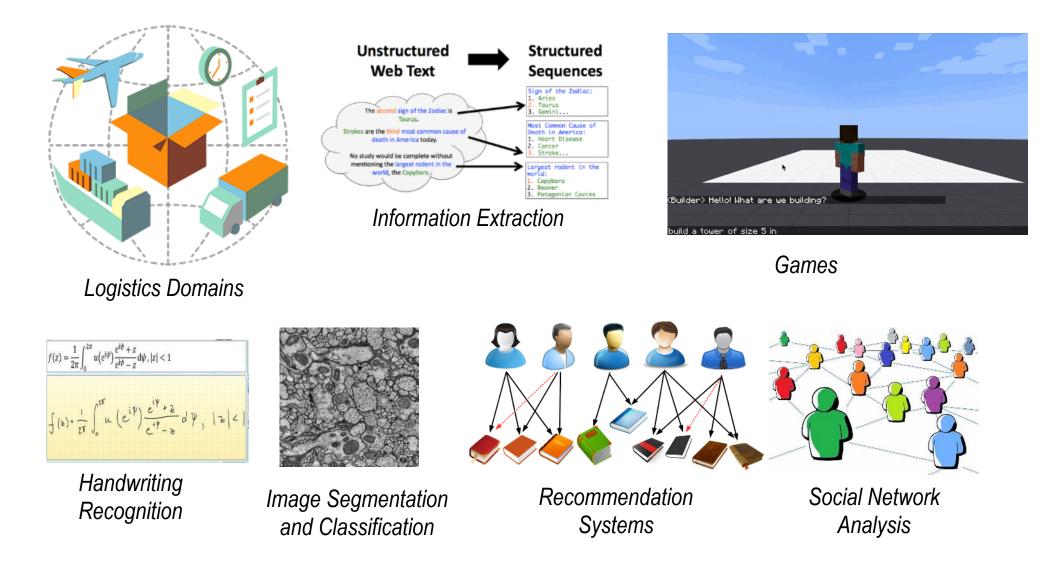
Fern et al. IJCAI 07; Natarajan et al. ILP08, ILP09; Natarajan et al. KAIS 11; Fern et al. JAIR 14; Kunapuli et al. ICDM 13; Odom et al. AAAI 15, AAMAS 16, ECML 16, ILP 16, AIME 15; Yang et al. ICDM 14, ECML 13; Macleod et al. CHASE 16; Natarajan et al. IJCAI 18; Das et al. AAAI 19, HMCL WS 17, AAMAS 18; KBS 18; Ramanan et al. BIBM 17, KR 18; Dhami et al. AIME 17, Smart Health 18, AI for Good 19; Kaur et al. ILP 17,19, IJAR 20; Hayes et al. KCAP 17; Kokel AAAI 20, ICAPS 21; Das et al. 20; Karanam AIME 21; Dhami AIME 21

(Our) 3 Steps to HAAI

Active advice seeking

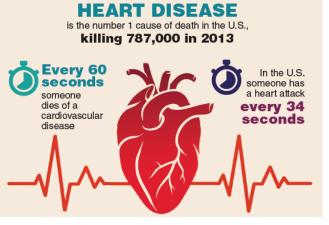
Advice taking Effective Learning Close the "loop" Allow "richer" Knows what it knows human inputs Learn "only" from data Effective More than a Asks what it does **not** know Efficient "mere labeler" Generalizable Student-teacher interaction Personalized Take advice and guidance Explainable **Teach the human!** . . . Allows for robust learning Ignores human knowledge

Several Real Applications

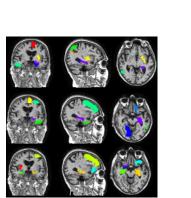


UTSouthwestern

Medical Center.



Cardiovascular Events Prediction and Treatment



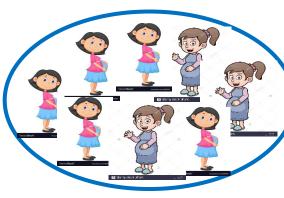
Alzheimer's disease prediction





The promise of discovery

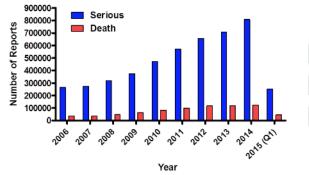
Predicting diabetes / cognition from sensors



 \mathcal{W} Wake Forest[®]

Baptist Health

Qualitative Knowledge Extraction

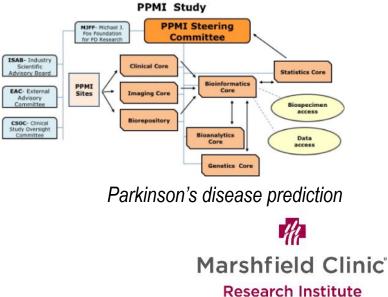


Medical record

Predicting rare diseases, post-partum

depression from survey data

Predicting the side-effects of drugs



(Our) 3 Steps to HAAI

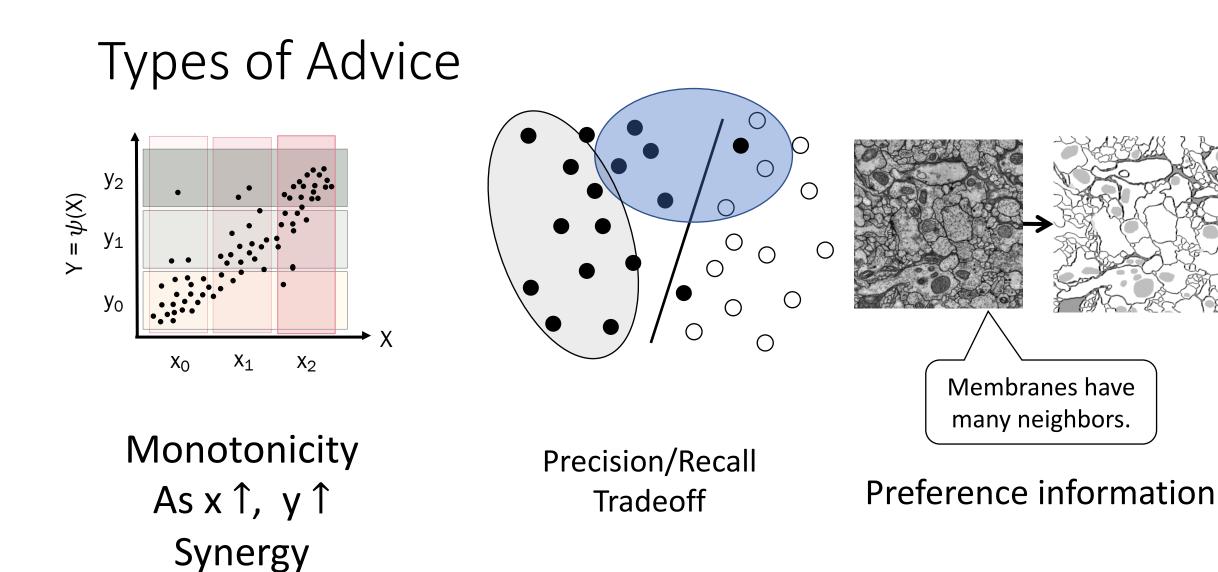
Active advice seeking

Advice taking

Effective Learning

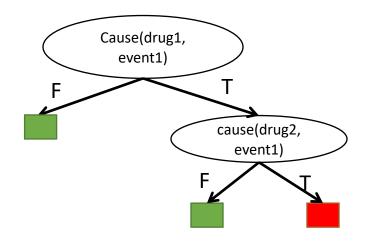
(Our) 3 Steps to HAAI

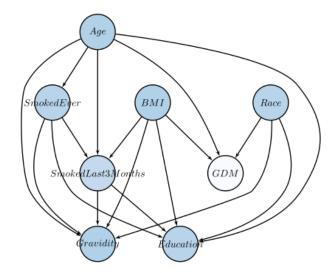
		Active advice seeking
	Advice taking	-
Effective Learning		-
<u>, </u>	Allow " richer " human inputs	
	More than a " mere labeler "	
	Take advice and guidance	
	Allows for robust learning	

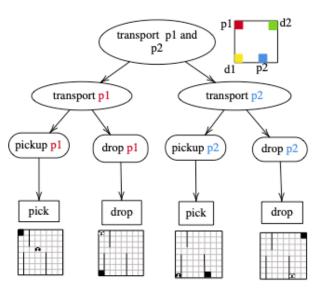


Yang 13, 14; Odom 15, 18; Das 18; Kokel 20

Types of Advice







Rules / Horn clauses

Causal Knowledge/ Influence information Task hierarchy

Example Frameworks for Advice Taking

- Probabilistic Graphical Models (Yang and Natarajan 2013, 2014; Ramanan 2018, 2021)
- Relational Probabilistic Models (Odom and Natarajan, 2016, 2018; Das et al 2018, 2021)
- Gradient Boosting (Odom & Natarajan 2018; Yang et al 2014; Kokel et al 2020)
- Deep Learning (Dhami et al 2021)
- Hierarchical Planning (Das et al 2018)
- Inverse Reinforcement Learning (Odom et al 2016)
- Imitation Learning (Odom and Natarajan 2018)
- Probabilistic Planning (Das et al 2018, 2019)
- Task-specific Abstractions (Kokel et al 2021)

Gradient Boosting

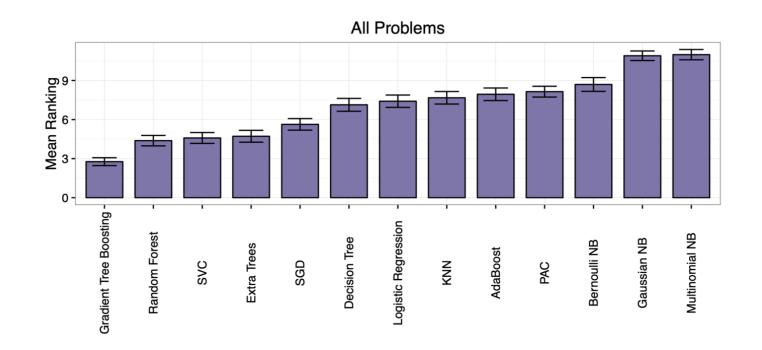
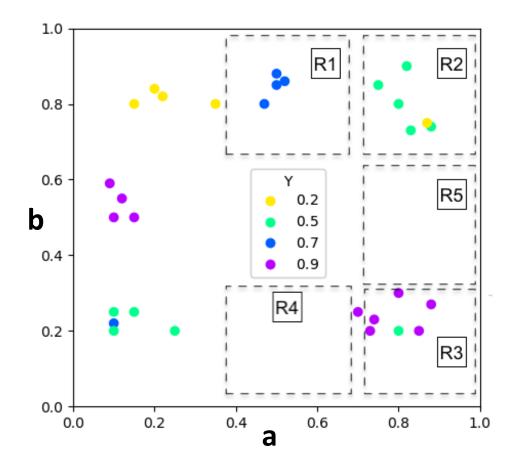
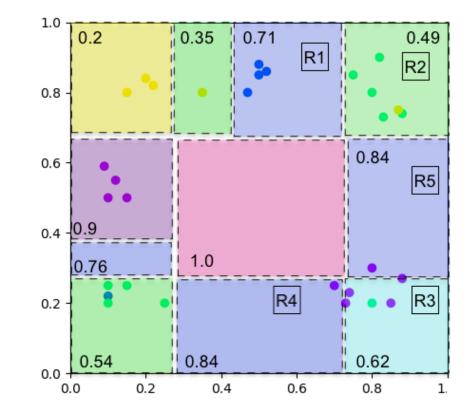


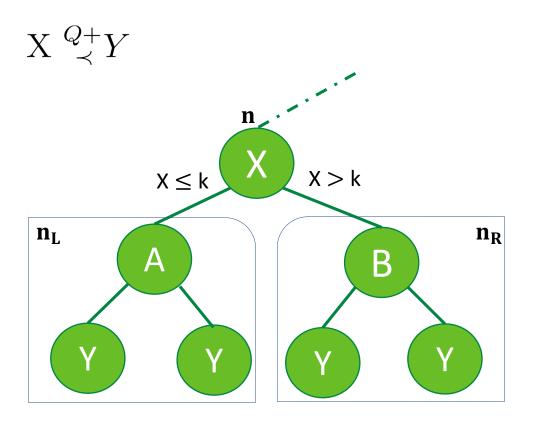
Fig. 1. Average ranking of the ML algorithms over all datasets. Error bars indicate the 95% confidence interval. Source: Olson et al. 2018 PSB

Sparse pockets





Boosting with Qualitative Constraints

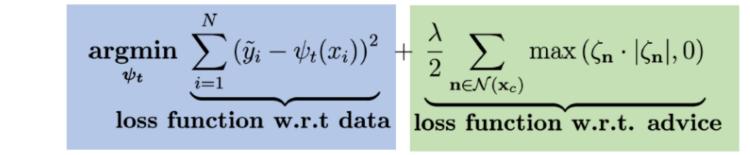


$$x_{1} < x_{2} \Rightarrow \mathbb{E}_{\psi}[x_{1}] \leq \mathbb{E}_{\psi}[x_{2}]$$
$$\mathbb{E}_{\psi}[\mathbf{n}_{L}] \leq \mathbb{E}_{\psi}[\mathbf{n}_{R}] + \varepsilon$$
$$\zeta_{n} - \begin{bmatrix} \mathbb{E}_{\psi}[\mathbf{n}_{L}] - \mathbb{E}_{\psi}[\mathbf{n}_{R}] - \varepsilon < 0 \end{bmatrix}$$
$$\operatorname{argmin} \sum_{\substack{i=1 \\ \text{loss function w.r.t data}}^{N} (y_{i} - \psi_{t}(x_{i}))^{2} + \frac{\lambda}{2} \sum_{\mathbf{n} \in \mathcal{N}(\mathbf{x}_{c})} \max \left(\zeta_{\mathbf{n}} \cdot |\zeta_{\mathbf{n}}|, 0 \right)$$

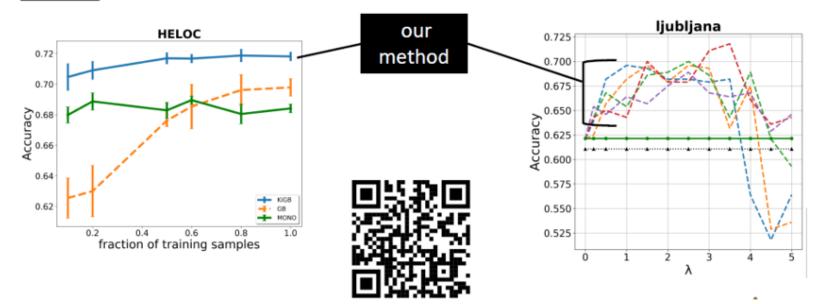
loss function w.r.t advice

Boosting with Qualitative Constraints

Objective



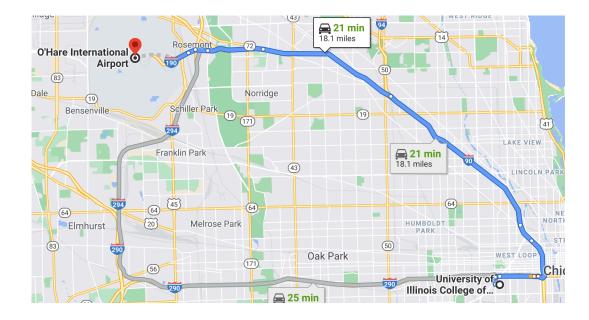
Results



Kokel et al. AAAI 2020

Sequential Decision Making

Abstractions

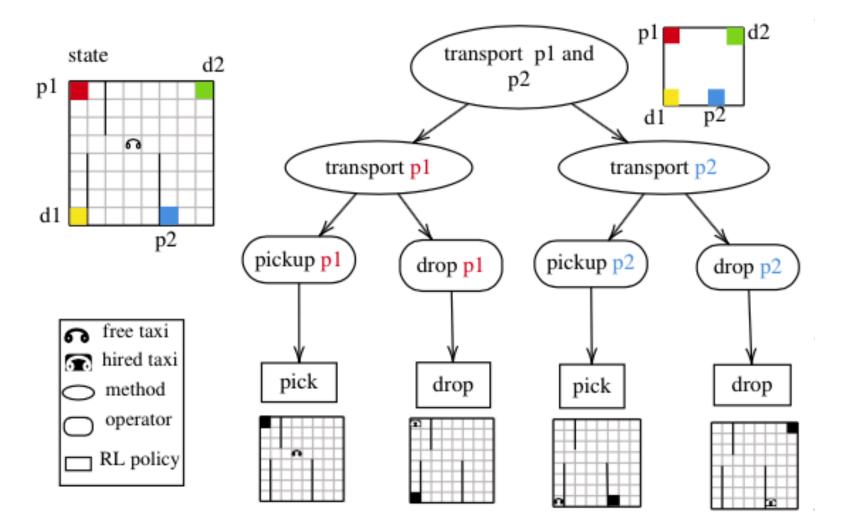




Execution

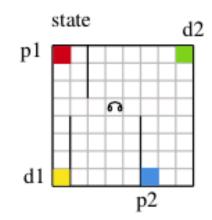
Planning

Influence information for Task-specific Abstraction

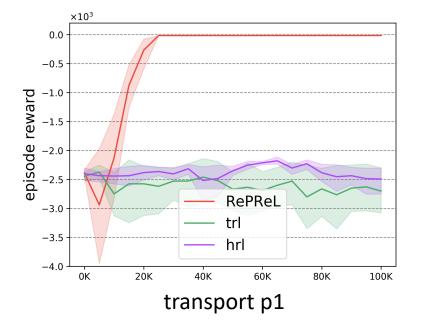


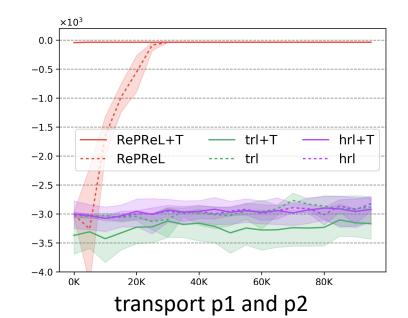
Influence information for Task-specific Abstraction

State	$egin{aligned} & ext{at}(p1,r), ext{taxi-at}(13), ext{dest}(p1,y), egin{aligned} & ext{at}(p1), egin{aligned} & ext{at}(p2,b), ext{dest}(p2,g), egin{aligned} & ext{at}(p2), egin{aligned} & ext{at}(p1), ext{at}(p1), ext{at}(p2,b), ext{dest}(p2,g), egin{aligned} & ext{at}(p2), ext{at}(p1), ext{at$
subtask	$\langle \ \mathrm{pickup}(P), \{P/p1, L/r\} angle$
D-FOCI	$ \{ taxi-at(L1), move(Dir) \} \xrightarrow{+1} taxi-at(L2) \\ \{ taxi-at(L1), move(Dir) \} \longrightarrow R \\ pickup(P): \\ \{ taxi-at(L1), at(P, L), in-taxi(P) \} \xrightarrow{+1} in-taxi(P) \\ pickup(P): in-taxi(P) \longrightarrow R_o $
Abstract state	$\{\operatorname{at}(\operatorname{p1},\operatorname{r}),\operatorname{taxi-at}(13),\neg\operatorname{in-taxi}(\operatorname{p1}),\operatorname{move}(\operatorname{Dir})\}$
	subtask D-FOCI



Experiments



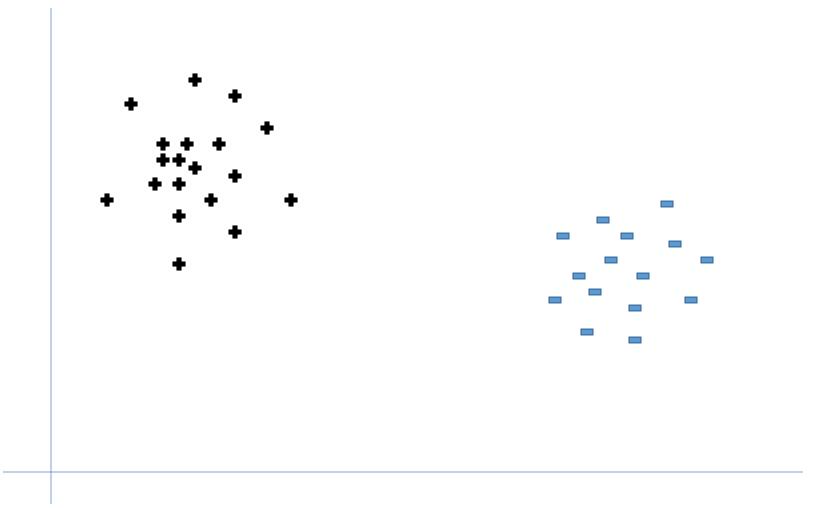


Sample efficiency Transfer across task and Generalization across objects

(Our) 3 Steps to HAAI

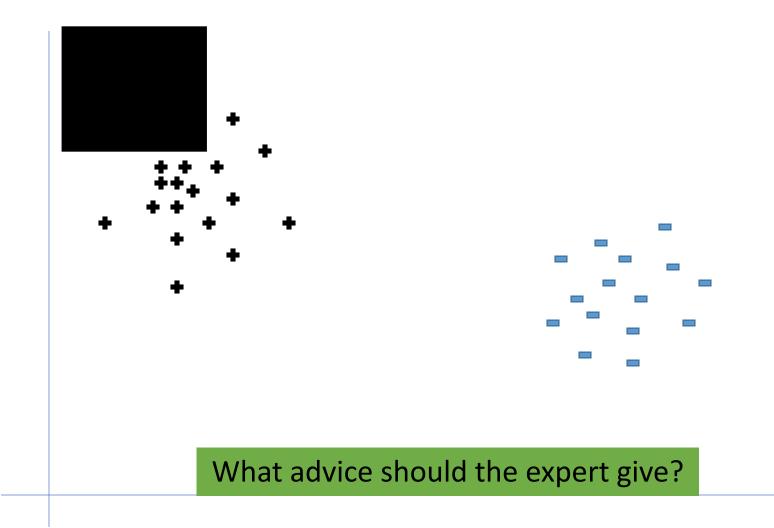
		Active advice seeking
	Advice taking	
Effective Learning	_	Close the " loop "
		Knows what it knows
		Asks what it does <u>not</u> know
		Student-teacher interaction
		Teach the human!

Knowledge-Based Learning



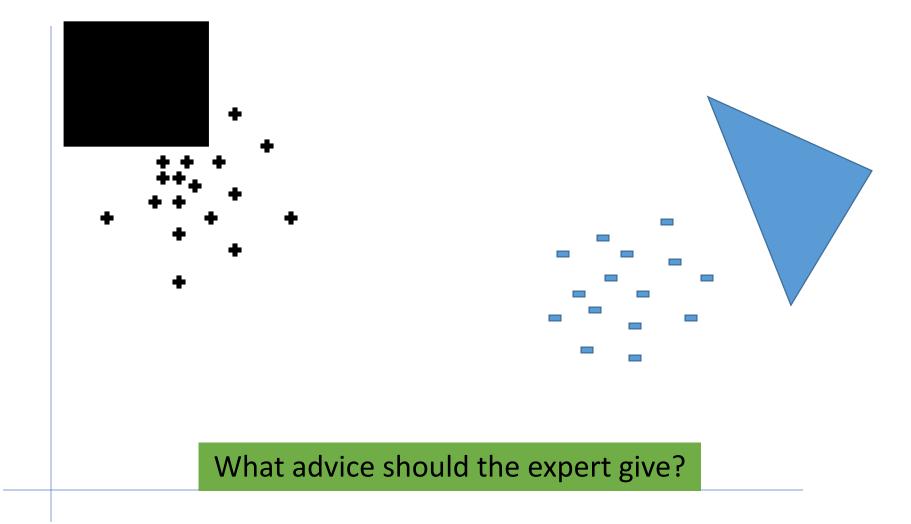
Fung et al. 02, Boutilier 02, Torrey et al. 05, Wiewiora et al. 03; Mangasarian et al 04, Kunapuli et al. 10,13

Knowledge-Based Learning

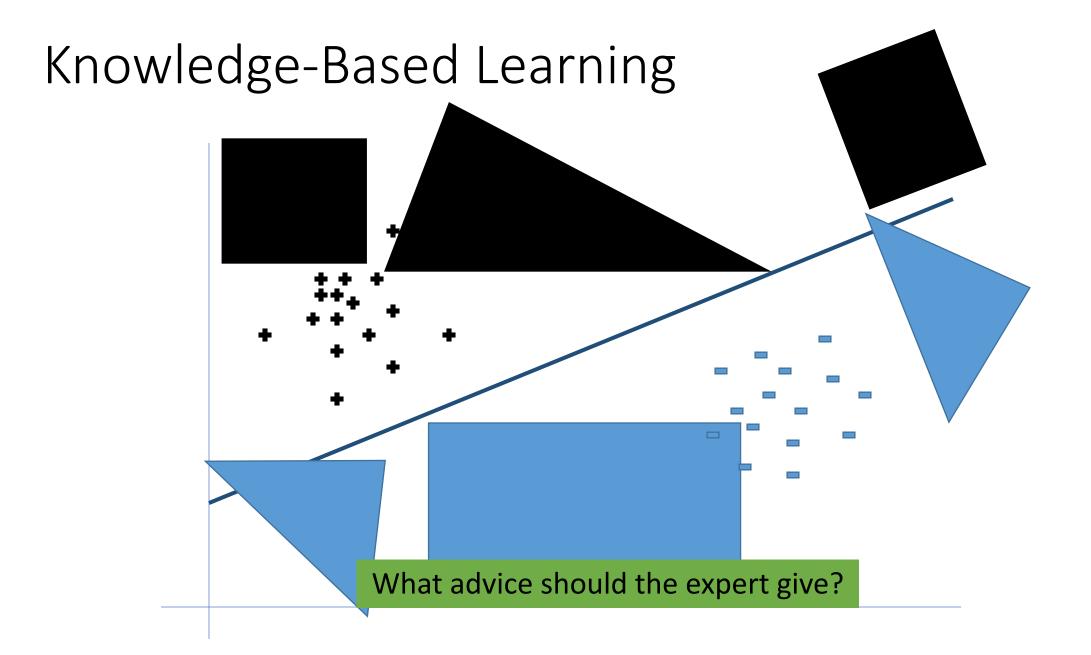


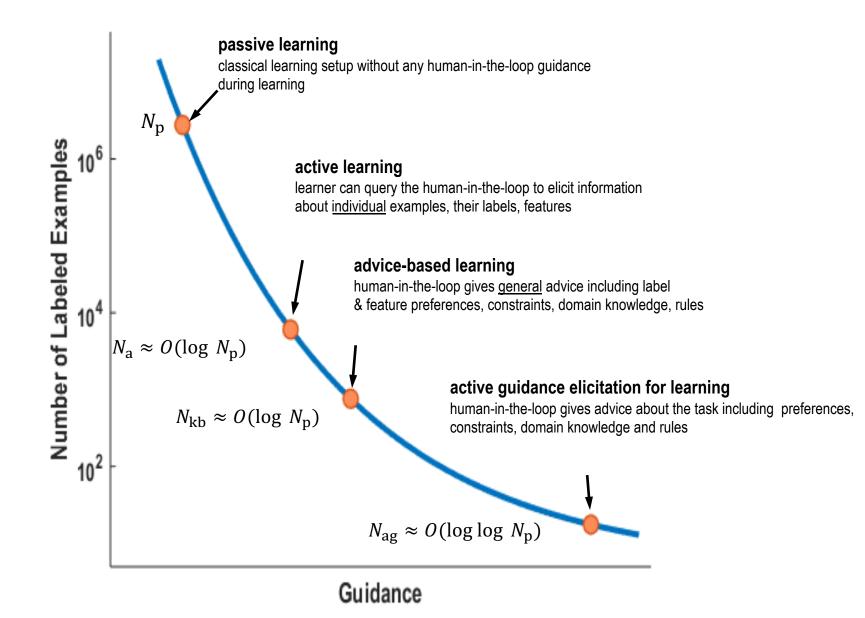
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Knowledge-Based Learning



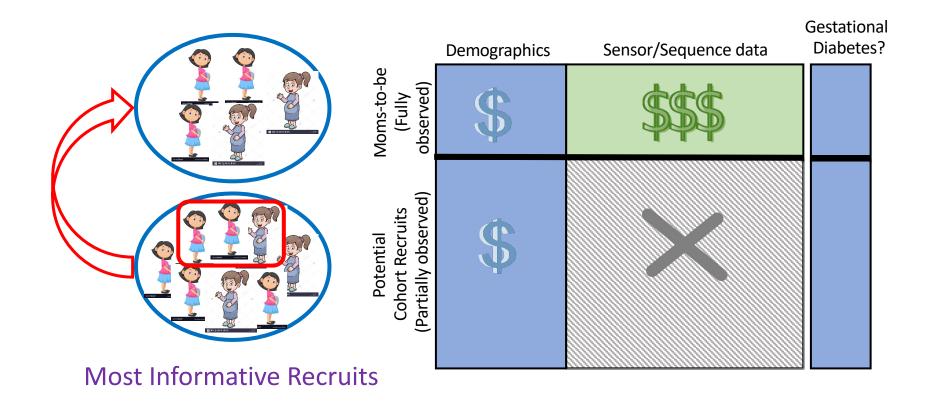
Fung et al. 02, Boutilier 02, Torrey et al. 05, Wiewiora et al. 03; Mangasarian et al 04, Kunapuli et al. 10,13





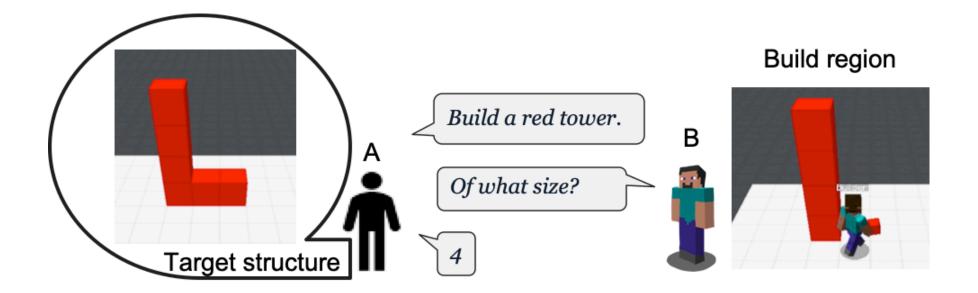
Active Feature Elicitation

Whom should we recruit?



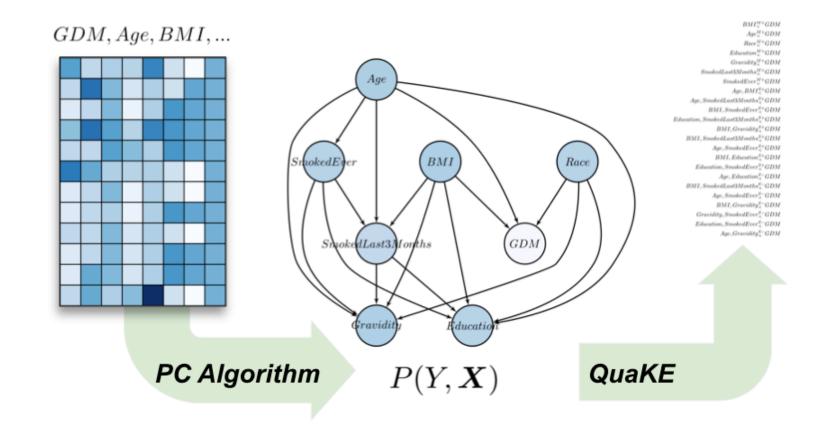
Natarajan et al. IJCAI '18; Das et al 2021

Collaborative Problem Solving



Achieve Generalization in One shot Learning

Extract Knowledge from Data



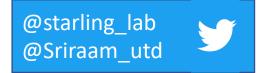
Miles to go before we sleep!



- Ensuring Human Trust explain decisions and solicit feedback Always include humans in decision-making
- Enabling Machine Fairness avoid bias in learning (social/economic/religious) impossible to maximize all notions of fairness
- Handling Ethical Issues white lies to make us eat healthy vs negotiation for profit
- Data vs Knowledge what if the evidence is contrary to human perception?
- Optimal/Rational vs. Human-like

Questions?

https://starling.utdallas.edu



Thanks!